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Moderate deviation for maximum likelihood estimators from single server queues



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Abstract Consider a single server queueing model which is observed over a continuous time interval (0, T], where *T* is determined by a suitable stopping rule. Let θ be the unknown parameter for the arrival process and $\hat{\theta}_T$ be the maximum likelihood estimator of θ . The main goal of this paper is to obtain a moderate deviation result of the maximum likelihood estimator for the single server queueing model under certain regular conditions.

Keywords GI/G/1 queue · Maximum likelihood estimator · Fisher information · Moderate deviation

2000 Mathematics Subject Classification 60K25 · 62F12

1 Introduction

Statistical analysis on queueing theory has come a long way in the past sixty years. A key component for the estimation of queueing parameter is maximum likelihood estimation. The problem of estimation of the unknown parameter using maximum likelihood estimation has been discussed in the literature over the last several years. The first theoretical treatment of the estimation problem was given by Clarke (1957), who derived maximum likelihood estimates of arrival and service rates in an M/M/1 queueing system. Billingsley's (1961) treatment of inference in Markov processes in general and Wolff's (1965) derivation of likelihood ratio tests and maximum likelihood estimates for queues that can be modeled as birth and death processes are other

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significant advances in this area. The papers by Cox (1965) and Goyal and Harris (1972) are worth mentioning. Since then, significant progress has occurred in adapting statistical procedures to various systems. Basawa and Prabhu (1981, 1988) and Acharya (1999) studied the asymptotic inference for single server queues, proving the consistency and asymptotic normality and finding the rate of convergence of maximum likelihood estimators in the queue GI/G/1, respectively. Recently, Acharya and Singh (2019) studied the asymptotic properties of the maximum likelihood estimator from single server queues using the martingale technique. Singh and Acharya (2019) discussed the bound for the equivalence of the Bayes and maximum likelihood estimator and also obtained the bound on the difference between the Bayes estimator from their true values of arrival and service rate parameter in an M/M/1 queue.

There has been recent interest to study the rate of convergence of the maximum likelihood estimator. Gao (2001) proved the results on moderate deviations for the maximum likelihood estimator for the case of independent and identically distributed observations and Xiao and Liu (2006) for the case of independent but not identically distributed observations. Miao and Chen (2010) gave a simpler proof to obtain these results under weaker conditions using Gärtner—Ellis theorem (cf. Dembo and Zeitouni (1998), Theorem 2.3.6, page 44). Miao and Wang (2014) improved the result in Miao and Chen (2010) by weakening the exponential integrability condition.

Our main aim in this paper is to study the problem of moderate deviations for the maximum likelihood estimator for single server GI/G/1 queueing model. Section 2 discusses the model of our interest and some elements of the maximum likelihood estimator. The main results are given in Section 3. In Section 4, we provide examples to illustrate our results.

2 GI/G/1 queueing model

Consider a single server queueing system in which the interarrival times $\{u_k, k \ge 1\}$ and the service times $\{v_k, k \ge 1\}$ are two independent sequences of independent and identically distributed nonnegative random variables with densities $f(u; \theta)$ and $g(v; \phi)$, respectively, where θ and ϕ are unknown parameters. Let us assume that fand g belong to the continuous exponential families given by

$$f(u;\theta) = a_1(u)\exp\{\theta h_1(u) - k_1(\theta)\},\tag{1}$$

$$g(v;\phi) = a_2(v)\exp\{\phi h_2(v) - k_2(\phi)\}.$$
(2)

and

$$f(u; \theta) = g(v; \phi) = 0$$
 on $(-\infty, 0)$,

where $\Theta_1 = \{\theta > 0 : k_1(\theta) < \infty\}$ and $\Theta_2 = \{\phi > 0 : k_2(\phi) < \infty\}$ are open subsets of \mathbb{R} . It is easy to see that, $k'_1(\theta) = E(h_1(u)), \sigma_1^2 = \sigma^2(\theta) = k''_1(\theta) =$ $var_{\theta}(h_1(u)), k'_2(\phi) = E(h_2(v)), \sigma_2^2 = \sigma_2^2(\phi) = k''_2(\phi) = var_{\phi}(h_2(v))$, respectively, the means and variances of the interarrival time and service time which are supposed to be finite. Here, dashes denotes the derivative with respect to parameters.

For simplicity, we assume that the initial customer arrives at time t = 0. Our sampling scheme is to observe the system over a continuous time interval [0, T],

where T is a suitable stopping time. The sample data consists of

$$\{A(T), D(T), u_1, u_2, \cdots, u_{A(T)}, v_1, v_2, \cdots, v_{D(T)}\},$$
(3)

where A(T) is the number of arrivals and D(T) is the number of departures during (0, T]. Obviously, no arrivals occur during $\left[\sum_{i=1}^{A(T)} u_i, T\right]$ and no departures during $\left[\gamma(T) + \sum_{i=1}^{D(T)} v_i, T\right]$, where $\gamma(T)$ is the total idle period in (0, T].

Some possible stopping rules to determine T are given below:

- Rule 1. Observe the system until a fixed time *t*. Here, T = t with probability one and A(T) and D(T) are both random variables.
- Rule 2. Observe the system until *d* departures have occurred so that D(T) = d. Here, $T = \gamma(T) + v_1 + v_2 + \dots + v_d$ and A(T) are random variables.
- Rule 3. Observe the system until *m* arrivals take place so that A(T) = m. Here, $T = u_1 + u_2 + u_3 + \dots + u_m$ and D(T) are random variables.
- Rule 4. Stop at the *nth* transition epoch. Here, T, A(T) and D(T) are all random variables and A(T) + D(T) = n.

Under rule 4, we stop either with an arrival or in a departure. If we stop with an arrival, then $\sum_{i=1}^{A(T)} u_i = T$ and no departures during $\left[\gamma(T) + \sum_{i=1}^{D(T)} v_i, T\right]$. Similarly, if we stop in a departure, then $\gamma(T) + \sum_{i=1}^{D(T)} v_i = T$ and there are no arrivals during $\left[\sum_{i=1}^{A(T)} u_i, T\right]$.

The likelihood function based on data (3) is given by

$$L_{T}(\theta,\phi) = \prod_{i=1}^{A(T)} f(u_{i},\theta) \prod_{i=1}^{D(T)} g(v_{i},\phi) \\ \times \left[1 - F_{\theta}[T - \sum_{i=1}^{A(T)} u_{i}] \right] \left[1 - G_{\phi}[T - \gamma(T) - \sum_{i=1}^{D(T)} v_{i}] \right],$$
(4)

where *F* and *G* are distribution functions corresponding to the densities *f* and *g*, respectively. The likelihood function $L_T(\theta, \phi)$ remains valid under all the stopping rules.

The approximate likelihood $L_T^a(\theta, \phi)$ is defined as

$$L_T^a(\theta, \phi) = \prod_{i=1}^{A(T)} f(u_i, \theta) \prod_{i=1}^{D(T)} g(v_i, \phi).$$
 (5)

The maximum likelihood estimates obtained from (5) are asymptotically equivalent to those obtained from (4) provided that the following two conditions are satisfied for $T \rightarrow \infty$:

$$(A(T))^{-1/2} \frac{\partial}{\partial \theta} \log \left[1 - F_{\theta} \left(T - \sum_{i=1}^{A(T)} u_i \right) \right] \stackrel{p}{\longrightarrow} 0$$

and



$$(D(T))^{-1/2} \frac{\partial}{\partial \phi} \log \left[1 - G_{\phi} \left(T - \gamma(T) - \sum_{i=1}^{D(T)} v_i \right) \right] \stackrel{p}{\longrightarrow} 0.$$

The implications of these conditions have been explained by Basawa and Prabhu (1988). From (5), we have the log-likelihood function

$$\ell_{T}(\theta,\phi) = \log L_{T}^{a}(\theta,\phi) = \ell_{T}(u_{1},u_{2},...,u_{A(T)};\theta) + \ell_{T}(v_{1},v_{2},...,v_{D(T)};\phi)$$

$$= \sum_{i=1}^{A(T)} \ell(u_{i};\theta) + \sum_{i=1}^{D(T)} \ell(v_{i};\phi)$$
(6)

with

$$\ell(u_i;\theta) = \log f(u_i;\theta) = \log a_1(u_i) + \theta h_1(u_i) - k_1(\theta)$$

and

$$\ell(v_i; \phi) = \log g(v_i; \phi) = \log a_2(v_i) + \phi h_2(v_i) - k_2(\phi).$$

Denote

$$\ell_T^{(1)}(u_1, u_2, \dots, u_{A(T)}; \theta) = \frac{\partial \ell_T(u_1, u_2, \dots, u_{A(T)}; \theta)}{\partial \theta}, \quad \ell^{(1)}(u_i; \theta) = \frac{\partial \log f(u_i; \theta)}{\partial \theta}$$

and

$$\ell_T^{(1)}(v_1, v_2, ..., v_{D(T)}; \phi) = \frac{\partial \ell_T(v_1, v_2, ..., v_{D(T)}; \phi)}{\partial \phi}, \quad \ell^{(1)}(v_i; \phi) = \frac{\partial \log g(v_i; \phi)}{\partial \phi}$$

The maximum likelihood estimators $\hat{\theta}_T = \hat{\theta}_T(u_1, u_2, ..., u_{A(T)})$ and $\hat{\phi}_T = \hat{\phi}_T(v_1, v_2, ..., v_{D(T)})$ of θ and ϕ are given by

$$\hat{\theta}_T = \eta_1^{-1} \left[(A(T))^{-1} \sum_{i=1}^{A(T)} h_1(u_i) \right], \tag{7}$$

$$\hat{\phi}_T = \eta_2^{-1} \left[(D(T))^{-1} \sum_{i=1}^{D(T)} h_2(v_i) \right], \tag{8}$$

respectively, where $\eta_i^{-1}(.)$ denotes the inverse functions of $\eta_i(.)$ for i = 1, 2 and

$$\eta_1(\theta) = E(h_1(u)) = k_1'(\theta)$$

and

$$\eta_2(\phi) = E(h_2(v)) = k_2'(\phi).$$

Since $\ell_T(v_1, v_2, ..., v_{D(T)})$, $\ell(v_i; \phi)$, and $\hat{\phi}_T$ are of the same form as in the case of θ , hereafter we will deal with only for the arrival process (for the parameter θ). However, the same can be done for the departure process.

Let

$$\underline{\theta}_T = \underline{\theta}_T(u_1, u_2, ..., u_{A(T)}) = \inf \left\{ \theta \in \theta : \ell_T^{(1)}(u_1, u_2, ..., u_{A(T)}; \theta) \le 0 \right\}$$

and

$$\bar{\theta}_T = \bar{\theta}_T(u_1, u_2, ..., u_{A(T)}) = \sup \left\{ \theta \in \theta : \ell_T^{(1)}(u_1, u_2, ..., u_{A(T)}; \theta) \ge 0 \right\}.$$

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$$\underline{\theta}_T(u_1, u_2, ..., u_{A(T)}) \le \hat{\theta}_T(u_1, u_2, ..., u_{A(T)}) \le \bar{\theta}_T(u_1, u_2, ..., u_{A(T)})$$

and, for every $\varepsilon > 0$,

$$P_{\theta}(\underline{\theta}_T \ge \theta + \varepsilon) \le P_{\theta}\left(\ell_T^{(1)}(u_1, u_2, ..., u_{A(T)}; \theta + \varepsilon) \ge 0\right) \le P_{\theta}(\bar{\theta}_T \ge \theta + \varepsilon)$$

and

$$P_{\theta}(\bar{\theta}_T \leq \theta - \varepsilon) \leq P_{\theta}\left(\ell_T^{(1)}(u_1, u_2, ..., u_{A(T)}; \theta - \varepsilon) \leq 0\right) \leq P_{\theta}(\underline{\theta}_T \leq \theta - \varepsilon).$$

We assume that the following conditions hold:

(C1) For each $\theta \in \Theta$, the derivatives

$$\ell^{(i)}(u;\theta) = \frac{\partial^{i} \log f(u;\theta)}{\partial \theta^{i}}, \ i = 1, 2, 3$$

exist for all $u \in R$.

(C2) For each $\theta \in \Theta$, there exists a neighbourhood $N(\theta, \delta)$ of θ for some $\delta > 0$ and non-negative measurable functions $A_i(u; \theta)$, i = 1, 2, 3 such that

$$\sup_{u \in R} \int_{R} A_{i}^{3}(u;\theta) f(u;\theta) dy < \infty, \ i = 1, 2, 3$$

and

$$\sup_{\theta' \in N(\theta,\delta)} |\ell^{(i)}(u;\theta')| \le A_i(u;\theta), \ i = 1, 2, 3$$

(C3) For each $\theta \in \Theta$, the probability density function $f(u; \theta)$ has a finite Fisher information, that is,

$$0 \le I(\theta) = E_{\theta} \left[\left(\frac{\partial \log f(u; \theta)}{\partial \theta} \right)^2 \right] < \infty$$

for all $u \in R$.

(C4) For each $\theta \in \Theta$, there exists $\mu = \mu(\theta) > 0$ and $\nu = \nu(\theta) > 0$ such that

$$\sup_{(x,\varepsilon)\in[-\mu,\mu]\times[-\nu,\nu]}\phi(x;\theta,\varepsilon)<\infty,$$

where

$$\phi(x;\theta,\varepsilon) = \sup_{u} E_{\theta} \left[\exp(x\ell^{(1)}(u_1;\theta+\varepsilon)) \right]$$

Under conditions (C1) - (C3), it can be easily seen that, for all $i \ge 1$,

$$E_{\theta}(\ell^{(1)}(u_i;\theta)) = 0 \tag{9}$$

and

$$E_{\theta}(\ell^{(2)}(u_i;\theta)) = -E_{\theta}[(\ell^{(1)}(u_i;\theta))^2] = -I(\theta).$$
(10)

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3 Main results

In this section, we study the problem of moderate deviation, i.e., the rate of convergence of the probability $P_{\theta}(\lambda(T)|\hat{\theta}_T - \theta| \ge \varepsilon)$, where

$$\lambda(T)\uparrow +\infty, \quad \frac{\lambda(T)}{\sqrt{A(T)}}\downarrow 0 \quad \text{as} \quad T\to\infty.$$

Theorem 1 Let conditions (C1) to (C4) hold, then

$$\liminf_{T \to \infty} \frac{\lambda^2(T)}{A(T)} \log P_\theta \left(\lambda(T)(\bar{\theta}_T - \theta) \ge \varepsilon \right) \ge -\frac{1}{2} I(\theta) \varepsilon^2, \tag{11}$$

$$\liminf_{T \to \infty} \frac{\lambda^2(T)}{A(T)} \log P_{\theta} \left(\lambda(T)(\underline{\theta}_T - \theta) \le -\varepsilon \right) \ge -\frac{1}{2} I(\theta) \varepsilon^2, \tag{12}$$

$$\limsup_{T \to \infty} \frac{\lambda^2(T)}{A(T)} \log P_{\theta} \left(\lambda(T)(\underline{\theta}_T - \theta) \ge \varepsilon \right) \le -\frac{1}{2} I(\theta) \varepsilon^2, \tag{13}$$

and

$$\limsup_{T \to \infty} \frac{\lambda^2(T)}{A(T)} \log P_\theta \left(\lambda(T)(\bar{\theta}_T - \theta) \le -\varepsilon \right) \le -\frac{1}{2} I(\theta) \varepsilon^2.$$
(14)

Furthermore,

$$\lim_{T \to \infty} \frac{\lambda^2(T)}{A(T)} \log P_{\theta} \left(\lambda(T) |\hat{\theta}_T - \theta| \le \varepsilon \right) = -\frac{1}{2} I(\theta) \varepsilon^2.$$
(15)

Theorem 2 Let conditions (C1) to (C4) hold, then, for any closed subset $\mathcal{F} \subset \Theta$, we have

$$\limsup_{T \to \infty} \frac{\lambda^2(T)}{A(T)} \log P_\theta \left(\lambda(T)(\hat{\theta}_T - \theta) \in \mathcal{F} \right) \le -\frac{1}{2} I(\theta) \inf_{x \in \mathcal{F}} \omega^2, \tag{16}$$

and, for any open subset $\mathcal{G} \subset \Theta$,

$$\liminf_{T \to \infty} \frac{\lambda^2(T)}{A(T)} \log P_{\theta} \left(\lambda(T)(\hat{\theta}_T - \theta) \in \mathcal{G} \right) \ge -\frac{1}{2} I(\theta) \inf_{x \in \mathcal{G}} \omega^2, \tag{17}$$

and, for any $\varepsilon > 0$,

$$\lim_{T \to \infty} \frac{\lambda^2(T)}{A(T)} \log P_{\theta} \left(\lambda(T) |\hat{\theta}_T - \theta| \ge \varepsilon \right) = -\frac{1}{2} I(\theta) \varepsilon^2.$$
(18)

To prove the above theorems, we need the following key lemma.

Lemma 1

$$\lim_{T \to \infty} \frac{\lambda^2(T)}{A(T)} \log P_{\theta} \left(\ell_T^{(1)}(u_1, u_2, ..., u_{A(T)}; \theta + \frac{\varepsilon}{\lambda(T)}) \ge 0 \right) = -\frac{1}{2} I(\theta) \varepsilon^2 \quad (19)$$

and

$$\lim_{T \to \infty} \frac{\lambda^2(T)}{A(T)} \log P_{\theta} \left(\ell_T^{(1)}(u_1, u_2, \dots, u_{A(T)}; \theta - \frac{\varepsilon}{\lambda(T)}) \le 0 \right) = -\frac{1}{2} I(\theta) \varepsilon^2.$$
(20)

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Proof From Taylor's expansion of $\ell(u; \theta)$ within the neighbourhood $N(\theta, \delta)$, we have

$$\sup_{u\in R} \left| \ell^{(1)}(u;\gamma) - \ell^{(1)}(u;\theta) - (\gamma-\theta)\ell^{(2)}(u;\theta) \right| \leq \frac{1}{2}(\gamma-\theta)^2 A_3(u;\theta).$$

Hence, for any $i \ge 1$,

$$\left|\ell^{(1)}\left(u_i;\theta+\frac{\varepsilon}{\lambda(T)}\right)-\ell^{(1)}(u_i;\theta)-\frac{\varepsilon}{\lambda(T)}\ell^{(2)}(u_i;\theta)\right|\leq \frac{\varepsilon^2}{2\lambda^2(T)}A_3(u_i;\theta).$$

Thus, by the condition (C2) and the Eqs. (9) and (10), it follows that

$$E_{\theta}\left[\ell^{(1)}\left(u_{i};\theta+\frac{\varepsilon}{\lambda(T)}\right)\right] = E_{\theta}\left[\ell^{(1)}(u_{i};\theta)\right] + \frac{\varepsilon}{\lambda(T)}E_{\theta}\left[\ell^{(2)}(u_{i};\theta)\right] + o\left(\frac{1}{\lambda(T)}\right)$$
$$= -I(\theta)\frac{\varepsilon}{\lambda(T)} + o\left(\frac{1}{\lambda(T)}\right).$$
(21)

Therefore, it follows that

$$\begin{split} P_{\theta} \left(\ell_{T}^{(1)} \left(u_{1}, u_{2}, ..., u_{A(T)}; \theta + \frac{\varepsilon}{\lambda(T)} \right) \geq 0 \right) \\ &= P_{\theta} \left[\frac{\lambda(T)}{A(T)} \sum_{i=1}^{A(T)} \left(\ell^{(1)} \left(u_{i}; \theta + \frac{\varepsilon}{\lambda(T)} \right) - E_{\theta} \left(\ell^{(1)} \left(u_{i}; \theta + \frac{\varepsilon}{\lambda(T)} \right) \right) \right) \\ &\geq -\frac{\lambda(T)}{A(T)} \sum_{i=1}^{A(T)} E_{\theta} \left(\ell^{(1)} \left(u_{i}; \theta + \frac{\varepsilon}{\lambda(T)} \right) \right) \right] \\ &= P_{\theta} \left[\frac{\lambda(T)}{A(T)} \sum_{i=1}^{A(T)} \left(\ell^{(1)} \left(u_{i}; \theta + \frac{\varepsilon}{\lambda(T)} \right) - E_{\theta} \left(\ell^{(1)} \left(u_{i}; \theta + \frac{\varepsilon}{\lambda(T)} \right) \right) \right) \\ &\geq I(\theta)\varepsilon + o(1) \right] \qquad (\text{using equation (21)}). \end{split}$$

We now compute the Cramér functional

$$\lim_{T \to \infty} \frac{\lambda^2(T)}{A(T)} \log E_{\theta} \left\{ \exp\left(\frac{x}{\lambda(T)} \sum_{i=1}^{A(T)} \left[\ell^{(1)}\left(u_i; \theta + \frac{\varepsilon}{\lambda(T)}\right) - E_{\theta}\left(\ell^{(1)}\left(u_i; \theta + \frac{\varepsilon}{\lambda(T)}\right)\right)\right] \right) \right\}$$

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for any $x \in R$. Applying Taylor's expansion, the condition (*C*4), and Eqs. (9), (10), (21) it follows that, for every $i \ge 1$, and for $x \in R$,

$$E_{\theta} \left\{ \exp\left(\frac{x}{\lambda(T)}\ell^{(1)}\left(u_{i};\theta+\frac{\varepsilon}{\lambda(T)}\right)\right) \right\}$$

$$=1+\frac{x}{\lambda(T)}E_{\theta} \left[\ell^{(1)}\left(u_{i};\theta+\frac{\varepsilon}{\lambda(T)}\right)\right]$$

$$+\frac{x^{2}}{2\lambda^{2}(T)}E_{\theta} \left(\left[\ell^{(1)}(u_{i};\theta+\frac{\varepsilon}{\lambda(T)})\right]^{2}\right)+o\left(\frac{1}{\lambda^{2}(T)}\right)$$

$$=1+\frac{1}{\lambda^{2}(T)}\left(\frac{x^{2}}{2}I(\theta)-x\varepsilon I(\theta)\right)+o\left(\frac{1}{\lambda^{2}(T)}\right).$$
(22)

Thus, it follows that

$$\begin{split} \log E_{\theta} \exp \left(\frac{x}{\lambda(T)} \left[\sum_{i=1}^{A(T)} \ell^{(1)} \left(u_i; \theta + \frac{\varepsilon}{\lambda(T)} \right) - \sum_{i=1}^{A(T)} E_{\theta} \left(\ell^{(1)} \left(u_i; \theta + \frac{\varepsilon}{\lambda(T)} \right) \right) \right] \right) \\ = \log \left[E_{\theta} \left\{ \exp \left(\frac{x}{\lambda(T)} \sum_{i=1}^{A(T)} \ell^{(1)} \left(u_i; \theta + \frac{\varepsilon}{\lambda(T)} \right) \right) \right\} \right] \\ + \left(-\frac{x}{\lambda(T)} \sum_{i=1}^{A(T)} E_{\theta} \left(\ell^{(1)} \left(u_i; \theta + \frac{\varepsilon}{\lambda(T)} \right) \right) \right) \\ = \log \left[\prod_{i=1}^{A(T)} E_{\theta} \left\{ \exp \left(\frac{x}{\lambda(T)} \ell^{(1)} \left(u_i; \theta + \frac{\varepsilon}{\lambda(T)} \right) \right) \right\} \right] \\ + \left(-\frac{x}{\lambda(T)} \sum_{i=1}^{A(T)} E_{\theta} \left(\ell^{(1)} \left(u_i; \theta + \frac{\varepsilon}{\lambda(T)} \right) \right) \right) \\ = \sum_{i=1}^{A(T)} \log \left[E_{\theta} \left\{ \exp \left(\frac{x}{\lambda(T)} \ell^{(1)} \left(u_i; \theta + \frac{\varepsilon}{\lambda(T)} \right) \right) \right\} \right] \\ + \left(-\frac{x}{\lambda(T)} \sum_{i=1}^{A(T)} E_{\theta} \left(\ell^{(1)} \left(u_i; \theta + \frac{\varepsilon}{\lambda(T)} \right) \right) \right) \end{split}$$

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$$=A(T)\log\left[1+\frac{1}{\lambda^{2}(T)}\left(\frac{x^{2}}{2}I(\theta)-x\varepsilon I(\theta)\right)+o\left(\frac{1}{\lambda^{2}(T)}\right)\right]$$
$$+\left(A(T)I(\theta)\frac{x\varepsilon}{\lambda^{2}(T)}+o\left(\frac{1}{\lambda^{2}(T)}\right)\right)$$
$$=A(T)\left[\frac{1}{\lambda^{2}(T)}\left(\frac{x^{2}}{2}I(\theta)-x\varepsilon I(\theta)\right)+o\left(\frac{1}{\lambda^{2}(T)}\right)\right]$$
$$+\left(A(T)I(\theta)\frac{x\varepsilon}{\lambda^{2}(T)}+o\left(\frac{1}{\lambda^{2}(T)}\right)\right)$$
$$=\frac{A(T)}{\lambda^{2}(T)}\frac{x^{2}}{2}I(\theta)+o\left(\frac{1}{\lambda^{2}(T)}\right)$$
(23)

Thus, we get that

$$\lim_{T \to \infty} \frac{\lambda^2(T)}{A(T)} \log E_{\theta} \left\{ \exp\left(\frac{x}{\lambda(T)} \sum_{i=1}^{A(T)} \left[\ell^{(1)}\left(u_i; \theta + \frac{\varepsilon}{\lambda(T)}\right) - E_{\theta}\left(\ell^{(1)}\left(u_i; \theta + \frac{\varepsilon}{\lambda(T)}\right)\right)\right] \sum_{i=1}^{A(T)} \right) \right\} = \frac{I(\theta)}{2} x^2.$$

Hence, by the Gärtner-Ellis theorem (cf. Gärtner (1977); Ellis (1984); Dembo and Zeitouni (1998, Theorem 2.3.6, page 44), we prove the result in Eq. (19) of Lemma 1. The result in Eq. (20) can be proved in similar manner. \Box

Proof of Theorem 1 Note that

$$P_{\theta}\left(\lambda(T)(\bar{\theta}_{T}-\theta)\geq\varepsilon\right)\geq P_{\theta}\left(\ell_{T}^{(1)}\left(u_{1},u_{2},...,u_{A(T)};\theta+\frac{\varepsilon}{\lambda(T)}\right)\geq0\right)$$

and

$$P_{\theta}\left(\lambda(T)(\underline{\theta}_{T}-\theta)\leq\varepsilon\right)\geq P_{\theta}\left(\ell_{T}^{(1)}\left(u_{1},u_{2},...,u_{A(T)};\theta+\frac{\varepsilon}{\lambda(T)}\right)\geq0\right).$$

Then, from Lemma 1, it is seen that the relation (11) and (13) hold. Using the similar arguments, (12), (14), and (15) can be proved.

Proof of Theorem 2 For a fixed close subset $\mathcal{F} \subset \Theta \subset R$, define $\omega_1 = \inf\{\omega > 0; \omega \in \mathcal{F}\}$ and $\omega_2 = \sup\{\omega < 0; \omega \in \mathcal{F}\}$. Let $I(\omega : \theta) = \frac{1}{2}I(\theta)\omega^2$. Then,

$$\begin{split} \limsup_{T \to \infty} \frac{\lambda^2(T)}{A(T)} \log P_{\theta} \left(\lambda(T)(\hat{\theta}_T - \theta) \in \mathcal{F} \right) \\ \leq \limsup_{T \to \infty} \frac{\lambda^2(T)}{A(T)} \log \left(P_{\theta} \left(\lambda(T)(\hat{\theta}_T - \theta) \leq \omega_2 \right) + \log P_{\theta} \left(\lambda(T)(\hat{\theta}_T - \theta) \geq \omega_1 \right) \right) \\ \leq \max\{-I(\omega_2, \theta), -I(\omega_1, \theta)\} = -\inf_{\omega \in \mathcal{F}} I(\omega : \theta) = -\frac{1}{2} I(\theta) \inf_{\omega \in \mathcal{F}} \omega^2. \end{split}$$

$$(24)$$

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Next, for a given open subset $\mathcal{G} \subset \Theta \subset R$, for $\forall \omega \in \mathcal{G}, \forall \varepsilon > 0$ such that $(\omega - \varepsilon, \omega + \varepsilon) \subset \mathcal{G}$, we have

$$P_{\theta}\left(\lambda(T)(\hat{\theta}_{T}-\theta)\in\mathcal{G}\right)\geq P_{\theta}\left(\omega-\varepsilon\leq\lambda(T)(\hat{\theta}_{T}-\theta)\leq\omega+\varepsilon\right)$$
$$=P_{\theta}\left(\sum_{i=1}^{A(T)}\ell^{(1)}\left(u_{i};\theta+\frac{\omega+\varepsilon}{\lambda(T)}\right)\right)$$
$$\leq 0, \sum_{i=1}^{A(T)}\ell^{(1)}\left(u_{i};\theta+\frac{\omega-\varepsilon}{\lambda(T)}\right)\geq 0\right).$$
(25)

From Eq. (6), we have

$$S_{A(T)} = \sum_{i=1}^{A(T)} \ell^{(1)}(u_i; \theta) = \sum_{i=1}^{A(T)} h_1(u_i) - A(T)k_1(\theta).$$

It is easy to see that the sequence $\{S_{A(T)}, A(T) \ge 1\}$ is a square integrable martingale with zero mean. Using the martingale central limit theorem (see Hall and Heyde (1980)), we have

$$P_{\theta}\left(\frac{1}{\sqrt{A(T)}}\sum_{i=1}^{A(T)}\ell^{(1)}(u_i;\theta) \ge \eta x\right) \to 1 - \Phi(\frac{\eta x}{\gamma_{\theta}})$$

for some $\gamma_{\theta} > 0$. Using similar arguments as in the Proof of Theorem 1, we have, $\forall x > 0$ and $\forall \eta > 0$,

$$\lim_{T \to \infty} \inf P_{\theta} \left(\lambda(T)(\hat{\theta}_{T} - \theta) \in \mathcal{G} \right) \\
\geq \frac{1}{x^{2}} \log \left(\Phi \left(\frac{x(\eta + I(\theta)(\omega + \varepsilon))}{\sigma_{\theta}} \right) - \Phi \left(\frac{x(\eta + I(\theta)(\omega - \varepsilon))}{\sigma_{\theta}} \right) \right).$$
(26)

Now, letting $\eta \to 0$ first, then $x \to \infty$, and finally $\varepsilon \to 0$, we get

$$\liminf_{T \to \infty} P_{\theta} \left(\lambda(T)(\hat{\theta}_T - \theta) \in \mathcal{G} \right) \ge -\frac{1}{2} I(\theta) \omega^2$$

which completes the proof, since we have chosen an arbitrary ω in \mathcal{G} in the above discussion.

4 Examples

4.1 M/M/1 queue

Let us consider the simplest of the queueing models used in practice, that is, an M/M/1 queue. The arrivals are assumed to occur in a Poisson process with rate θ and the service time distribution follows exponential distribution with mean $1/\phi$. Here,

$$f(u, \theta) = \theta e^{-\theta u}$$
 and $g(v, \phi) = \phi e^{-\phi v}$.

0

The log-likelihood function becomes

$$\ell_T(\theta, \phi) = A(T)\log \theta - \theta \sum_{i=1}^{A(T)} u_i + D(T)\log \phi - \phi \sum_{i=1}^{D(T)} v_i$$

and the maximum likelihood estimators are

$$\hat{\theta}_T = \left[\frac{\sum_{i=1}^{A(T)} u_i}{A(T)}\right]^{-1}, \, \hat{\phi}_T = \left[\frac{\sum_{i=1}^{D(T)} v_i}{D(T)}\right]^{-1}.$$
(27)

For this example, the logarithm of interarrival density function is $\ell(u_i; \theta) = \log \theta - \theta u_i$, and the first three derivatives are $\ell^{(1)}(u_i; \theta) = \frac{1}{\theta} - u_i$, $\ell^{(2)}(u_i; \theta) = -\frac{1}{\theta^2}$, and $\ell^{(3)}(u_i; \theta) = \frac{2}{\theta^3}$. It is easy to see that conditions (*C*1) to (*C*4) hold. Hence, the results of Section 3 hold for $\hat{\theta}_T$, the maximum likelihood estimator of θ with the Fisher information $I(\theta) = \frac{1}{\theta^2}$.

4.2 $E_k/M/1$ queue

Here, we consider the $E_k/M/1$ queueing model. The interarrival and service time densities are

$$f(u,\theta) = \frac{\theta(\theta u)^{k-1} e^{-\theta u}}{(k-1)!} \quad \text{and} \quad g(v,\phi) = \phi e^{-\phi v}.$$

The log-likelihood function is

$$\ell_T(\theta, \phi) = kA(T)\log\theta + (k-1)\sum_{i=1}^{A(T)}\log u_i - \theta \sum_{i=1}^{A(T)} u_i - A(T)\log[(k-1)!] + D(T)\log\phi - \phi \sum_{i=1}^{D(T)} v_i$$

and the maximum likelihood estimators are

$$\hat{\theta}_T = \left[\frac{\sum_{i=1}^{A(T)} u_i}{kA(T)}\right]^{-1}, \, \hat{\phi}_T = \left[\frac{\sum_{i=1}^{D(T)} v_i}{D(T)}\right]^{-1}.$$
(28)

The logarithm of interarrival density function is

$$\ell(u_i; \theta) = k \log \theta + (k-1) \log u_i - \theta u_i - \log[(k-1)!].$$

So, $\ell^{(1)}(u_i; \theta) = \frac{k}{\theta} - u_i$, $\ell^{(2)}(u_i; \theta) = -\frac{k}{\theta^2}$, $\ell^{(3)}(u_i; \theta) = \frac{2k}{\theta^3}$, and the Fisher information $I(\theta) = \frac{k}{\theta^2}$. One can easily find that conditions (C1) to (C4) hold. Hence, the results of Section 3 hold for $\hat{\theta}_T$, the maximum likelihood estimator of θ .

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Authors' contributions

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